## Examination II for PHYS 6220/7220, Fall 2015

1. A particle of mass m and angular momentum  $\ell$  moves in a central force field and has an equation of the orbit given by  $r = a(1 + cos(\theta))$ , where a is a positive constant of appropriate dimensions.

(a) Find the form of the potential V(r). The answer should only contain the constants a,  $\ell$  and m. (2 points)

(b) A particle of mass M approaches this center of force from far away with initial speed  $V_0$  and impact parameter b. In what follows completely ignore the influence of the first particle of mass m on M. Derive and hence draw the shape of the effective potential,  $V_e(r)$ , that the mass M experiences. Justify with precise mathematical reasoning the shape of  $V_e(r)$ . Mark any critical points ( $r_c$ ) that may occur on this graph giving expressions for these points  $r_c$  and the corresponding  $V_e(r_c)$ . (4 points)

(c) From the answer in part (b) determine the critical value of the impact parameter of M above which the particle fails to reach the origin? Quantitative answers in parts (b) and (c) should only contain the constants a, b,  $\ell$ , m, M and V<sub>0</sub>. (**2 points**)

2. A right handed Cartesian frame S is rotated about its fixed origin to obtain another frame S'. The initial set of right handed unit vectors along the X, Y and Z axes of S are  $\mathbf{e_1}$ ,  $\mathbf{e_2}$  and  $\mathbf{e_3}$ , respectively Those along the new axes, X', Y' and Z', of the frame S' are  $\mathbf{e_1}$ ',  $\mathbf{e_2}$ ' and  $\mathbf{e_3}$ ', respectively. It is known that  $(\mathbf{e_1})^{\mathrm{T}} = (1, 0, 0)$  and  $(\mathbf{e_3})^{\mathrm{T}} = (0, 0, 1)$ . Similarly it is known that  $(\mathbf{e_1}')^{\mathrm{T}} = (1/5)(4, 1, \sqrt{8}), (\mathbf{e_2}')^{\mathrm{T}} = (1/5)(1, 4, -\sqrt{8})$  and  $(\mathbf{e_3'})^{\mathrm{T}} = (1/5)(-\sqrt{8}, \sqrt{8}, 3)$ . Express all angles in radians in the interval  $[0, 2\pi]$ .

(a) Find the matrix corresponding to this rotation. Do not convert any matrix elements to decimals. (**5 points**)

(b) Check that it is indeed a rotation matrix. (1 point)

(c) Find the angle of rotation  $\Phi$ . (1 point)

(d) Find the unit vector along the axis of rotation **n**. (2 points)

(e) If this rotation was carried out not about a single axis and angle but by three Euler angle rotations then find the three Euler angles  $\theta$ ,  $\psi$ , and  $\phi$ . Assume  $\theta$  is an acute angle. (3 points)