

Problem 4.15

(a) $\Psi(\mathbf{r}, t) = \frac{1}{\sqrt{2}} (\psi_{211} e^{-iE_2 t/\hbar} + \psi_{21-1} e^{-iE_2 t/\hbar}) = \frac{1}{\sqrt{2}} (\psi_{211} + \psi_{21-1}) e^{-iE_2 t/\hbar}; \quad E_2 = \frac{E_1}{4} = -\frac{\hbar^2}{8ma^2}$

From Problem 4.11(b):

$$\psi_{211} + \psi_{21-1} = -\frac{1}{\sqrt{\pi a}} \frac{1}{8a^2} r e^{-r/2a} \sin \theta (e^{i\phi} - e^{-i\phi}) = -\frac{i}{\sqrt{\pi a}} \frac{1}{4a^2} r e^{-r/2a} \sin \theta \sin \phi.$$

$$\boxed{\Psi(\mathbf{r}, t) = -\frac{i}{\sqrt{2\pi a}} \frac{1}{4a^2} r e^{-r/2a} \sin \theta \sin \phi e^{-iE_2 t/\hbar}.}$$

(b)

$$\begin{aligned} \langle V \rangle &= \int |\Psi|^2 \left(-\frac{e^2}{4\pi\epsilon_0} \frac{1}{r} \right) d^3\mathbf{r} = \frac{1}{(2\pi a)(16a^4)} \left(-\frac{e^2}{4\pi\epsilon_0} \right) \int \left(r^2 e^{-r/a} \sin^2 \theta \sin^2 \phi \right) \frac{1}{r} r^2 \sin \theta dr d\theta d\phi \\ &= \frac{1}{32\pi a^5} \left(-\frac{\hbar^2}{ma^2} \right) \int_0^\infty r^3 e^{-r/a} dr \int_0^\pi \sin^3 \theta d\theta \int_0^{2\pi} \sin^2 \phi d\phi = -\frac{\hbar^2}{32\pi ma^6} (3!a^4) \left(\frac{4}{3} \right) (\pi) \\ &= \boxed{-\frac{\hbar^2}{4ma^2} = \frac{1}{2} E_1 = \frac{1}{2} (-13.6 \text{eV}) = -6.8 \text{eV}} \quad (\text{independent of } t). \end{aligned}$$

But 1

4.15(b) Smart way to answer!

$$\langle V \rangle = \int \left(\frac{-e^2}{4\pi\epsilon_0 r} \right) \left(\frac{1}{2} \right) |Y_{211} + Y_{21-1}|^2 d^3\vec{r}$$

Note $Y_{211} + Y_{21-1} = R_{21}(r) [Y_1^1(\theta, \phi) + Y_1^{-1}(\theta, \phi)]$

Now $d^3\vec{r} = r^2 dr d\Omega$

where $d\Omega = \sin\theta d\theta d\phi$

Also $\int (Y_{l'}^{m'})^* Y_l^m d\Omega = \delta_{l,l'} \delta_{m,m'}$

$$\Rightarrow \int d\Omega |Y_{211} + Y_{21-1}|^2 = |R_{21}|^2 [1 + 1 + 0 + 0] \\ = 2|R_{21}|^2$$

$$\Rightarrow \langle V \rangle = \frac{-e^2}{4\pi\epsilon_0} \int_0^\infty |R_{21}|^2 r dr$$

$$= \frac{-e^2}{4\pi\epsilon_0} \times \frac{1}{24a^5} \int_0^\infty r^3 e^{-r/a} dr \quad (\text{using Table 4.7})$$

$$= \frac{-e^2}{4\pi\epsilon_0} \times \frac{1}{24a} \int_0^\infty x^3 e^{-x} dx$$

$$= \left[\frac{-e^2}{4\pi\epsilon_0 a} \right] \times \frac{1}{4} = \frac{E_1}{2} = \frac{-13.6 \text{ eV}}{2} = -6.8 \text{ eV}$$

Problem 4.18

$$\langle f|L_{\pm}g\rangle = \langle f|L_x g\rangle \pm i\langle f|L_y g\rangle = \langle L_x f|g\rangle \pm i\langle L_y f|g\rangle = \langle (L_x \mp iL_y)f|g\rangle = \langle L_{\mp}f|g\rangle, \text{ so } (L_{\pm})^{\dagger} = L_{\mp}.$$

Now, using Eq. 4.112, in the form $L_{\mp}L_{\pm} = L^2 - L_z^2 \mp \hbar L_z$:

$$\begin{aligned}\langle f_l^m | L_{\mp}L_{\pm} f_l^m \rangle &= \langle f_l^m | (L^2 - L_z^2 \mp \hbar L_z) f_l^m \rangle = \langle f_l^m | [\hbar^2 l(l+1) - \hbar^2 m^2 \mp \hbar^2 m] f_l^m \rangle \\&= \hbar^2 [l(l+1) - m(m \pm 1)] \langle f_l^m | f_l^m \rangle = \hbar^2 [l(l+1) - m(m \pm 1)] \\&= \langle L_{\pm} f_l^m | L_{\pm} f_l^m \rangle = \langle A_l^m f_l^{m\pm 1} | A_l^m f_l^{m\pm 1} \rangle = |A_l^m|^2 \langle f_l^{m\pm 1} | f_l^{m\pm 1} \rangle = |A_l^m|^2.\end{aligned}$$

Problem 4.21

(a)

$$\begin{aligned}
 L_+ L_- f &= -\hbar^2 e^{i\phi} \left(\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right) \left[e^{-i\phi} \left(\frac{\partial f}{\partial \theta} - i \cot \theta \frac{\partial f}{\partial \phi} \right) \right] \\
 &= -\hbar^2 e^{i\phi} \left\{ e^{-i\phi} \left[\frac{\partial^2 f}{\partial \theta^2} - i \left(-\csc^2 \theta \frac{\partial f}{\partial \phi} + \cot \theta \frac{\partial^2 f}{\partial \theta \partial \phi} \right) \right] \right. \\
 &\quad \left. + i \cot \theta \left[-ie^{-i\phi} \left(\frac{\partial f}{\partial \theta} - i \cot \theta \frac{\partial f}{\partial \phi} \right) + e^{-i\phi} \left(\frac{\partial^2 f}{\partial \phi \partial \theta} - i \cot \theta \frac{\partial^2 f}{\partial \phi^2} \right) \right] \right\} \\
 &= -\hbar^2 \left(\frac{\partial^2 f}{\partial \theta^2} + i \csc^2 \theta \frac{\partial f}{\partial \phi} - i \cot \theta \frac{\partial^2 f}{\partial \theta \partial \phi} + \cot \theta \frac{\partial f}{\partial \theta} - i \cot^2 \theta \frac{\partial f}{\partial \phi} + i \cot \theta \frac{\partial^2 f}{\partial \phi \partial \theta} + \cot^2 \theta \frac{\partial^2 f}{\partial \phi^2} \right) \\
 &= -\hbar^2 \left[\frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \cot^2 \theta \frac{\partial^2}{\partial \phi^2} + i(\csc^2 \theta - \cot^2 \theta) \frac{\partial}{\partial \phi} \right] f, \quad \text{so} \\
 L_+ L_- &= -\hbar^2 \left(\frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \cot^2 \theta \frac{\partial^2}{\partial \phi^2} + i \frac{\partial}{\partial \phi} \right). \quad \text{QED}
 \end{aligned}$$

(b) Equation 4.129 $\Rightarrow L_z = \frac{\hbar}{i} \frac{\partial}{\partial \phi}$, Eq. 4.112 $\Rightarrow L^2 = L_+ L_- + L_z^2 - \hbar L_z$, so, using (a):

$$\begin{aligned}
 L^2 &= -\hbar^2 \left(\frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \cot^2 \theta \frac{\partial^2}{\partial \phi^2} + i \frac{\partial}{\partial \phi} \right) - \hbar^2 \frac{\partial^2}{\partial \phi^2} - \hbar \left(\frac{\hbar}{i} \right) \frac{\partial}{\partial \phi} \\
 &= -\hbar^2 \left(\frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + (\cot^2 \theta + 1) \frac{\partial^2}{\partial \phi^2} + i \frac{\partial}{\partial \phi} - i \frac{\partial}{\partial \phi} \right) = -\hbar^2 \left(\frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right) \\
 &= -\hbar^2 \left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right]. \quad \text{QED}
 \end{aligned}$$