

Problem 4.27

(a)

$$\chi^\dagger \chi = |A|^2(9 + 16) = 25|A|^2 = 1 \Rightarrow \boxed{A = 1/5.}$$

(b)

$$\langle S_x \rangle = \chi^\dagger S_x \chi = \frac{1}{25} \frac{\hbar}{2} (-3i \ 4) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 3i \\ 4 \end{pmatrix} = \frac{\hbar}{50} (-3i \ 4) \begin{pmatrix} 4 \\ 3i \end{pmatrix} = \frac{\hbar}{50} (12i + 12i) = \boxed{0.}$$

$$\langle S_y \rangle = \chi^\dagger S_y \chi = \frac{1}{25} \frac{\hbar}{2} (-3i \ 4) \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 3i \\ 4 \end{pmatrix} = \frac{\hbar}{50} (-3i \ 4) \begin{pmatrix} -4i \\ -3 \end{pmatrix} = \frac{\hbar}{50} (-12 - 12) = \boxed{-\frac{12}{25} \hbar.}$$

$$\langle S_z \rangle = \chi^\dagger S_z \chi = \frac{1}{25} \frac{\hbar}{2} (-3i \ 4) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 3i \\ 4 \end{pmatrix} = \frac{\hbar}{50} (-3i \ 4) \begin{pmatrix} 3i \\ -4 \end{pmatrix} = \frac{\hbar}{50} (9 - 16) = \boxed{-\frac{7}{50} \hbar.}$$

(c)

$$\langle S_x^2 \rangle = \langle S_y^2 \rangle = \langle S_z^2 \rangle = \frac{\hbar^2}{4} \text{ (always, for spin } 1/2\text{), so } \sigma_{S_x}^2 = \langle S_x^2 \rangle - \langle S_x \rangle^2 = \frac{\hbar^2}{4} - 0, \quad \boxed{\sigma_{S_x} = \frac{\hbar}{2}.}$$

$$\sigma_{S_y}^2 = \langle S_y^2 \rangle - \langle S_y \rangle^2 = \frac{\hbar^2}{4} - \left(\frac{12}{25}\right)^2 \hbar^2 = \frac{\hbar^2}{2500} (625 - 576) = \frac{49}{2500} \hbar^2, \quad \boxed{\sigma_{S_y} = \frac{7}{50} \hbar.}$$

$$\sigma_{S_z}^2 = \langle S_z^2 \rangle - \langle S_z \rangle^2 = \frac{\hbar^2}{4} - \left(\frac{7}{50}\right)^2 \hbar^2 = \frac{\hbar^2}{2500} (625 - 49) = \frac{576}{2500} \hbar^2, \quad \boxed{\sigma_{S_z} = \frac{12}{25} \hbar.}$$

(d)

$$\sigma_{S_x} \sigma_{S_y} = \frac{\hbar}{2} \cdot \frac{7}{50} \hbar \stackrel{?}{\geq} \frac{\hbar}{2} |\langle S_z \rangle| = \frac{\hbar}{2} \cdot \frac{7}{50} \hbar \quad (\text{right at the uncertainty limit}). \checkmark$$

$$\sigma_{S_y} \sigma_{S_z} = \frac{7}{50} \hbar \cdot \frac{12}{25} \hbar \stackrel{?}{\geq} \frac{\hbar}{2} |\langle S_x \rangle| = 0 \quad (\text{trivial}). \checkmark$$

$$\sigma_{S_z} \sigma_{S_x} = \frac{12}{25} \hbar \cdot \frac{\hbar}{2} \stackrel{?}{\geq} \frac{\hbar}{2} |\langle S_y \rangle| = \frac{\hbar}{2} \cdot \frac{12}{25} \hbar \quad (\text{right at the uncertainty limit}). \checkmark$$

Problem 4.32

(a) Using Eqs. 4.151 and 4.163:

$$c_+^{(x)} = \chi_+^{(x)\dagger} \chi = \frac{1}{\sqrt{2}} (1 \ 1) \begin{pmatrix} \cos \frac{\alpha}{2} e^{i\gamma B_0 t/2} \\ \sin \frac{\alpha}{2} e^{-i\gamma B_0 t/2} \end{pmatrix} = \frac{1}{\sqrt{2}} \left[\cos \frac{\alpha}{2} e^{i\gamma B_0 t/2} + \sin \frac{\alpha}{2} e^{-i\gamma B_0 t/2} \right].$$

$$\begin{aligned} P_+^{(x)}(t) &= |c_+^{(x)}|^2 = \frac{1}{2} \left[\cos \frac{\alpha}{2} e^{-i\gamma B_0 t/2} + \sin \frac{\alpha}{2} e^{i\gamma B_0 t/2} \right] \left[\cos \frac{\alpha}{2} e^{i\gamma B_0 t/2} + \sin \frac{\alpha}{2} e^{-i\gamma B_0 t/2} \right] \\ &= \frac{1}{2} \left[\cos^2 \frac{\alpha}{2} + \sin^2 \frac{\alpha}{2} + \sin \frac{\alpha}{2} \cos \frac{\alpha}{2} (e^{i\gamma B_0 t} + e^{-i\gamma B_0 t}) \right] \\ &= \frac{1}{2} \left[1 + 2 \sin \frac{\alpha}{2} \cos \frac{\alpha}{2} \cos(\gamma B_0 t) \right] = \boxed{\frac{1}{2} [1 + \sin \alpha \cos(\gamma B_0 t)]}. \end{aligned}$$

(b) From Problem 4.29(a): $\chi_+^{(y)} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}$.

$$c_+^{(y)} = \chi_+^{(y)\dagger} \chi = \frac{1}{\sqrt{2}} (1 \ -i) \begin{pmatrix} \cos \frac{\alpha}{2} e^{i\gamma B_0 t/2} \\ \sin \frac{\alpha}{2} e^{i\gamma B_0 t/2} \end{pmatrix} = \frac{1}{\sqrt{2}} \left[\cos \frac{\alpha}{2} e^{i\gamma B_0 t/2} - i \sin \frac{\alpha}{2} e^{i\gamma B_0 t/2} \right];$$

$$\begin{aligned} P_+^{(y)}(t) &= |c_+^{(y)}|^2 = \frac{1}{2} \left[\cos \frac{\alpha}{2} e^{-i\gamma B_0 t/2} + i \sin \frac{\alpha}{2} e^{i\gamma B_0 t/2} \right] \left[\cos \frac{\alpha}{2} e^{i\gamma B_0 t/2} - i \sin \frac{\alpha}{2} e^{-i\gamma B_0 t/2} \right] \\ &= \frac{1}{2} \left[\cos^2 \frac{\alpha}{2} + \sin^2 \frac{\alpha}{2} + i \sin \frac{\alpha}{2} \cos \frac{\alpha}{2} (e^{i\gamma B_0 t} - e^{-i\gamma B_0 t}) \right] \\ &= \frac{1}{2} \left[1 - 2 \sin \frac{\alpha}{2} \cos \frac{\alpha}{2} \sin(\gamma B_0 t) \right] = \boxed{\frac{1}{2} [1 - \sin \alpha \sin(\gamma B_0 t)]}. \end{aligned}$$

(c)

$$\chi_+^{(z)} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}; \quad c_+^{(z)} = (1 \ 0) \begin{pmatrix} \cos \frac{\alpha}{2} e^{i\gamma B_0 t/2} \\ \sin \frac{\alpha}{2} e^{-i\gamma B_0 t/2} \end{pmatrix} = \cos \frac{\alpha}{2} e^{i\gamma B_0 t/2}; \quad P_+^{(z)}(t) = |c_+^{(z)}|^2 = \boxed{\cos^2 \frac{\alpha}{2}}.$$

Problem 4.29

(a)

$$S_y = \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}; \quad \begin{vmatrix} -\lambda & -i\hbar/2 \\ i\hbar/2 & -\lambda \end{vmatrix} = \lambda^2 - \frac{\hbar^2}{4} \Rightarrow \lambda = \pm \frac{\hbar}{2} \text{ (of course).}$$

$$\frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \pm \frac{\hbar}{2} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} \Rightarrow -i\beta = \pm\alpha; \quad |\alpha|^2 + |\beta|^2 = 1 \Rightarrow |\alpha|^2 + |\alpha|^2 = 1 \Rightarrow \alpha = \frac{1}{\sqrt{2}}.$$

$$\boxed{\chi_+^{(y)} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}; \quad \chi_-^{(y)} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -i \end{pmatrix}.}$$

(b)

$$c_+ = \left(\chi_+^{(y)}\right)^\dagger \chi = \frac{1}{\sqrt{2}} (1 \ -i) \begin{pmatrix} a \\ b \end{pmatrix} = \frac{1}{\sqrt{2}}(a - ib); \quad \boxed{+\frac{\hbar}{2}, \text{ with probability } \frac{1}{2}|a - ib|^2.}$$

$$c_- = \left(\chi_-^{(y)}\right)^\dagger \chi = \frac{1}{\sqrt{2}} (1 \ i) \begin{pmatrix} a \\ b \end{pmatrix} = \frac{1}{\sqrt{2}}(a + ib); \quad \boxed{-\frac{\hbar}{2}, \text{ with probability } \frac{1}{2}|a + ib|^2.}$$

$$\begin{aligned} P_+ + P_- &= \frac{1}{2} [(a^* + ib^*)(a - ib) + (a^* - ib^*)(a + ib)] \\ &= \frac{1}{2} [|a|^2 - ia^*b + iab^* + |b|^2 + |a|^2 + ia^*b - iab^* + |b|^2] = |a|^2 + |b|^2 = 1. \checkmark \end{aligned}$$