

Linear Algebra

AI

A vector space consists of a set of vectors $\{\alpha, \beta, \gamma, \dots\}$ together with a set of scalars $\{a, b, c, \dots\}$ which is closed under two operations

(1) Addition

$$\alpha + \beta = \text{another vector} \\ \forall \alpha, \beta \in S$$

(2) Scalar Multiplication

$$a\alpha = \text{also a vector } \forall a, \alpha.$$

$\forall \equiv$ "for all", \equiv means "is equivalent to" or it means "is defined as"

Addition is commutative

$$\Leftrightarrow \alpha + \beta = \beta + \alpha$$

and associative

$$\alpha + (\beta + \gamma) = (\alpha + \beta) + \gamma$$

$\exists \equiv$ "there exists"

There exists a zero or null vector such that

$$1\alpha 7 + 107 = 1\alpha 7, \quad \forall 1\alpha 7 \in S$$

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$\exists \equiv$ "such that," $\in \equiv$ "belongs to"

We will in general call the set of vectors in the vector space S .

The scalars will be complex numbers i.e. their set is \mathbb{C} . The set of real numbers will be called \mathbb{R} .

Any scalar a can be expressed as

$$a \equiv a_r + i a_i, \quad \text{where } i \equiv \sqrt{-1}$$

$$a_r, a_i \in \mathbb{R}.$$

$$a \equiv r e^{i\theta} \equiv r [\cos \theta + i \sin \theta]$$

$$\Leftrightarrow a_r \equiv r \cos \theta, \quad a_i \equiv r \sin \theta$$

$r, \theta \in \mathbb{R}$

$$\theta \equiv \arctan \left[\frac{a_i}{a_r} \right]$$

$$r = \sqrt{a_r^2 + a_i^2}, \quad r \geq 0.$$

$$|a| \equiv r, \quad a^* \equiv a_r - i a_i$$

$$|a|^2 \equiv a a^* \equiv a^* a$$

$\forall 1\alpha 7 \in S, \exists$ an additive inverse of $1\alpha 7$ denoted by $-1\alpha 7 \ni 1\alpha 7 - 1\alpha 7 = 107$

Scalar multiplication is ~~no~~ distributive with respect to vector addition

$$\Rightarrow a(\alpha\gamma + \beta\gamma) = a\alpha\gamma + a\beta\gamma$$

and with respect to scalar addition

$$(a+b)\alpha\gamma = a\alpha\gamma + b\alpha\gamma$$

It is also associative wrt scalar multiplication

$$a(b\alpha\gamma) = (ab)\alpha\gamma$$

wrt \equiv "with respect to".

Also $0\alpha\gamma = \mathbf{0}$ and $1\alpha\gamma = \alpha\gamma$.

A linear combination of vectors is of the form $a\alpha\gamma + b\beta\gamma + c\gamma\gamma + \dots$

Two vectors $\alpha\gamma$ and $\beta\gamma$ are defined to be linearly independent iff

the equation $a\alpha\gamma + b\beta\gamma = \mathbf{0}$

has a unique solution $a = b = 0$ for the scalars a and b .

iff \equiv "if and only if".

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Consider a set of m vectors $|e_i\rangle$

$i = 1, 2, \dots, m$. They are said to be linearly independent iff the equation

$$\sum_{i=1}^m a_i |e_i\rangle = |0\rangle \rightarrow \textcircled{\text{NI}}$$

has the unique solution $a_i = 0, \forall i = 1, \dots, m$.

The maximum value of m is called the dimension of the space n .

I.e. n is the maximum number of linearly independent vectors that can be found. A set of n linearly independent vectors is called a basis because any vector $|\alpha\rangle \in S$ can be expressed as

$$|\alpha\rangle = \sum_{i=1}^n a_i |e_i\rangle$$

So set $\{|e_i\rangle, i = 1, \dots, n\}$ obeying $\textcircled{\text{NI}} \exists$

$a_i = 0, \forall i = 1, \dots, n$ is called a basis.

It is said to span the space. Such a set is also called complete.

Vectors in S such as $|\alpha\rangle$ are called kets. For every ket $|\alpha\rangle$ there exists another vector denoted by $\langle\alpha|$ in the

space dual to S called S_d .

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$$|\alpha\rangle \in S \iff \langle\alpha| \in S_d$$

$A \implies B \equiv$ "Statement A implies Statement B"

$A \iff B \equiv$ "Statement A implies Statement B

and Statement B implies Statement A",

An inner product between two vectors

$|\alpha\rangle$ and $|\beta\rangle$ is denoted by

$\langle\alpha|\beta\rangle$ and it belongs to \mathbb{C}

I.e. $\langle\alpha|\beta\rangle \in \mathbb{C}$.

For every equation with kets we have an equation with bras. We obtain it by replacing all kets with bras and all scalars by their complex conjugates,

$$\therefore |\alpha\rangle = a|\beta\rangle + c|\gamma\rangle$$

$$\iff \langle\alpha| = \langle\beta|a^* + \langle\gamma|c^*$$

\therefore if $d = \langle\delta|\omega\rangle$ then

$$d^* = \langle\omega|\delta\rangle, \text{ i.e. } \langle\delta|\omega\rangle^* = \langle\omega|\delta\rangle$$

$$\text{and } \langle \delta/\omega \rangle = \langle \omega/\delta \rangle^*$$

Also inner products have the following properties

$$\langle \alpha/\alpha \rangle \geq 0, \quad \langle \alpha/\alpha \rangle = 0 \Leftrightarrow |\alpha\rangle = |0\rangle$$

$$\langle \alpha/[b|\beta\rangle + c|\gamma\rangle] = b\langle \alpha/\beta \rangle + c\langle \alpha/\gamma \rangle$$

The norm of a vector is defined as

$$\| |\alpha\rangle \| \equiv \sqrt{\langle \alpha/\alpha \rangle}$$

A unit vector is one whose norm is 1

$$|\alpha\rangle \text{ is a unit vector } \Leftrightarrow \langle \alpha/\alpha \rangle = 1.$$

A set of vectors $|\alpha_i\rangle$, $i=1, \dots, m$ is orthogonal (perpendicular) iff

$$\langle \alpha_i/\alpha_j \rangle = 0, \quad \forall i \neq j.$$

Furthermore if $\langle \alpha_i/\alpha_i \rangle = 1$, $\forall i=1, \dots, m$ then the set is called orthonormal.

If $m = n = \text{dimension of } S$ then the set is called an orthonormal basis.

We define the Kronecker delta function or discrete delta function by

$$\delta_{ij} = \begin{cases} 1 & , \quad \forall i=j \\ 0 & , \quad \forall i \neq j \end{cases}$$

e.g. $\delta_{1,2} = 0$, $\delta_{5,5} = 1$

$\therefore 1 \neq 2$, $\therefore 5 = 5$

$\therefore \equiv$ "because"

For an orthonormal set then

$$\langle \alpha_i | \alpha_j \rangle = \delta_{ij}$$

An operator or transformation denoted by a capital letter with a cap on it

\hat{T} is an instruction or recipe to change one vector to another in a precise manner.

$$|\alpha'\rangle = \hat{T}|\alpha\rangle$$

A linear operator is one that has the following property

$$\hat{T}(a|\alpha\rangle + b|\beta\rangle) = a(\hat{T}|\alpha\rangle) + b(\hat{T}|\beta\rangle)$$

$$\forall |\alpha\rangle, |\beta\rangle \in S \text{ and } \forall a, b \in \mathbb{C},$$

A linear transformation \hat{T} is completely defined by its effect on a basis set $\{ |e_i\rangle, i=1, \dots, n \}$.

$$\text{Let } \hat{T}|e_j\rangle = \sum_{i=1}^n T_{ij}|e_i\rangle, \quad j=1, \dots, n.$$

where $T_{ij} \in \mathbb{C}$.

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$$\text{Let } |\alpha\rangle = \sum_{j=1}^n a_j |e_j\rangle$$

Suppose the basis is orthonormal.

$$\text{Then } \langle e_i | e_j \rangle = \langle e_j | e_i \rangle = \delta_{ij}$$

$$\begin{aligned} \therefore \langle e_i | \hat{T} | e_j \rangle &= \langle e_i | \sum_{k=1}^n T_{kj} | e_k \rangle \\ &= \sum_{k=1}^n T_{kj} \langle e_i | e_k \rangle = \sum_{k=1}^n T_{kj} \delta_{ik} \\ &= T_{ij} \end{aligned}$$

$$\Rightarrow T_{ij} = \langle e_i | \hat{T} | e_j \rangle$$

T_{ij} are called the matrix elements of the operator \hat{T} .

$$\begin{aligned} \text{Similarly } \langle e_i | \alpha \rangle &= \sum_{j=1}^n a_j \langle e_i | e_j \rangle \\ &= \sum_{j=1}^n a_j \delta_{ij} = a_i \end{aligned}$$

$$\Rightarrow a_i = \langle e_i | \alpha \rangle$$

$$a_i^* = \langle \alpha | e_i \rangle$$

a_i are the components or projections of $|\alpha\rangle$ of $\langle m|e_i\rangle$.

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i.e. $a_i \equiv$ component of $|\alpha\rangle$ along $|e_i\rangle$

or projection of $|\alpha\rangle$ on $|e_i\rangle$.

$$\hat{T}|\alpha\rangle = \sum_{j=1}^n a_j (\hat{T}|e_j\rangle) = \sum_{j=1}^n a_j \left(\sum_{i=1}^n T_{ij} |e_i\rangle \right)$$

$$= \sum_{j=1}^n \sum_{i=1}^n T_{ij} a_j |e_i\rangle$$

$$= \sum_{i=1}^n \left[\sum_{j=1}^n T_{ij} a_j \right] |e_i\rangle$$

$$= \sum_{i=1}^n a'_i |e_i\rangle \text{ where } a'_i \equiv \sum_{j=1}^n T_{ij} a_j$$

$\Rightarrow \hat{T}$ takes a vector $|\alpha\rangle$ with components $\{a_i\}$ to a vector

$\hat{T}|\alpha\rangle$ with components $\{a'_i\}$.

$$\Rightarrow \begin{bmatrix} a'_1 \\ a'_2 \\ \vdots \\ a'_n \end{bmatrix} = \begin{bmatrix} T_{11} & \dots & T_{1n} \\ T_{21} & \dots & T_{2n} \\ \vdots & & \vdots \\ T_{n1} & \dots & T_{nn} \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix}$$

$$\Leftrightarrow a'_i = \langle e_i | \hat{T} | \alpha \rangle, \quad \langle e_i | \hat{T} | e_j \rangle, \quad \langle e_i | \alpha \rangle$$

\parallel \parallel \parallel
 T_{ij} a_i

This means $|\alpha\rangle$ is defined by a column matrix $\begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix}$, $\langle\alpha|$ by a

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row matrix $[a_1^* \ a_2^* \ \dots \ a_n^*]_{1 \times n}$

and the operator \hat{T} by a square matrix

$$\begin{bmatrix} T_{11} & T_{12} & \dots & T_{1n} \\ T_{21} & T_{22} & \dots & T_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ T_{n1} & T_{n2} & \dots & T_{nn} \end{bmatrix}_{n \times n}$$

We will denote such correspondence by \leftrightarrow , $\therefore |\alpha\rangle \leftrightarrow \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix}$.

If $\hat{U} = \hat{S} + \hat{T}$ then

$$\begin{aligned} U_{ij} &= \langle e_i | \hat{U} | e_j \rangle = \langle e_i | \hat{S} + \hat{T} | e_j \rangle \\ &= \langle e_i | \hat{S} | e_j \rangle + \langle e_i | \hat{T} | e_j \rangle \\ &= S_{ij} + T_{ij} = U_{ij} \end{aligned}$$

Suppose now $\hat{U} = \hat{S} \hat{T}$. This means if $|\alpha'\rangle = \hat{T} |\alpha\rangle$, $|\alpha''\rangle = \hat{S} |\alpha'\rangle$

$$\Rightarrow |\alpha''\rangle = \hat{S} \hat{T} |\alpha\rangle = \hat{U} |\alpha\rangle$$

All

What is U_{ij} in terms of S_{ij} and T_{ij} .

For this we first note that \hat{T} with matrix elements $\{T_{ij}\}$ can be written as

$$\hat{T} = \sum_{i=1}^n \sum_{j=1}^n T_{ij} |e_i\rangle \langle e_j|$$

We check this now.

$$\begin{aligned} \therefore \langle e_m | \hat{T} | e_n \rangle &= \sum_i \sum_j T_{ij} \langle e_m | e_i \rangle \langle e_j | e_n \rangle \\ &= \sum_i \sum_j T_{ij} \delta_{mi} \delta_{jn} = T_{mn} \end{aligned}$$

as expected.

Now consider the identity operator which leaves all vectors unchanged.

$$\Rightarrow \hat{I} |\alpha\rangle = |\alpha\rangle,$$

$$\Rightarrow \hat{I} |e_j\rangle = |e_j\rangle$$

$$\Rightarrow \langle e_i | \hat{I} | e_j \rangle = \langle e_i | e_j \rangle = \delta_{ij}$$

$$\therefore \hat{I} = \sum_i \sum_j \delta_{ij} |e_i\rangle \langle e_j| = \sum_i |e_i\rangle \langle e_i|$$

It can be easily seen that

$$\hat{I} \hat{T} = \hat{T} \hat{I} = \hat{T}, \quad \forall \hat{T}.$$

$$\text{Now } \hat{U} = \hat{S} \hat{T} \Rightarrow U_{ij} = \langle e_i | \hat{S} \hat{T} | e_j \rangle$$

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$$\text{Since } \hat{S} = \hat{S} \hat{I} \text{ we get } \hat{S} \hat{T} = \hat{S} \hat{I} \hat{T}$$

$$\therefore \hat{S} \hat{T} = \sum_{k=1}^n \hat{S} | e_k \rangle \langle e_k | \hat{T}$$

$$\begin{aligned} \therefore U_{ij} &= \sum_{k=1}^n \langle e_i | \hat{S} | e_k \rangle \langle e_k | \hat{T} | e_j \rangle \\ &= \sum_{k=1}^n S_{ik} T_{kj} \end{aligned}$$

This is just the formula for product of two matrices. Every operator corresponds to a matrix denoted by \overline{T} so that

$$T_{ij} \equiv (\overline{T})_{ij} \equiv \langle e_i | \sum_m \sum_n T_{mn} | e_m \rangle \langle e_n | e_j \rangle$$

$$\therefore \overline{U} = \overline{S} \overline{T}$$

The Hermitian conjugate of an operator \hat{T} is defined as another operator \hat{T}^\dagger \exists

$$\hat{T}^\dagger \equiv \left[\sum_i \sum_j T_{ij} | e_i \rangle \langle e_j | \right]^\dagger$$

$$\equiv \sum_i \sum_j T_{ij}^* | e_j \rangle \langle e_i |$$

$$\therefore (\hat{T}^\dagger)_{mn} = \langle e_m | \hat{T}^\dagger | e_n \rangle = T_{nm}^*$$

$$\therefore (\hat{T}^\dagger)_{mn} = [(\hat{T})_{nm}]^*$$

If $|\beta\rangle = \hat{T}|\alpha\rangle$ then

$$\langle\beta| = \langle\alpha|\hat{T}^\dagger$$

Also $\overline{\overline{T}}^\dagger \equiv (\overline{\overline{T}}^\dagger)^* \equiv (\overline{\overline{T}}^*)^T$

If $\overline{\overline{T}}$ has elements T_{ij} then the transpose of the matrix $\overline{\overline{T}}$ is defined as

$$\overline{\overline{T}}^T \ni (\overline{\overline{T}}^T)_{ij} = (\overline{\overline{T}})_{ji}$$

i.e. flip all rows with columns.

A unitary operator \hat{U} is defined as one for which

$$\hat{U}^\dagger \hat{U} = \hat{I} = \hat{U} \hat{U}^\dagger$$

A unitary matrix $\ni \overline{\overline{U}}^\dagger \overline{\overline{U}} = \overline{\overline{U}} \overline{\overline{U}}^\dagger = \overline{\overline{I}}$.

A matrix is called Hermitian iff

$$\overline{\overline{T}}^\dagger = \overline{\overline{T}}, \text{ i.e. } T_{ij} = T_{ji}^*$$

An operator is called Hermitian iff

$$\hat{T}^\dagger = \hat{T}$$

An anti-Hermitian operator or matrix follow the equations

$$\hat{T}^\dagger = -\hat{T} \quad \text{or} \quad \overline{\hat{T}}^\dagger = -\overline{\hat{T}}.$$

Consider a vector $|\alpha\rangle$ operated ^{ed} on by some linear operator $\hat{T} \Rightarrow$

$$\hat{T}|\alpha\rangle = \lambda|\alpha\rangle, \quad \text{where } \lambda \in \mathbb{C},$$

is a constant. Such an equation is called an eigen-value equation, the constant λ is called an eigenvalue and $|\alpha\rangle$ is an eigenvector of \hat{T} .

If \hat{T} is Hermitian, i.e. $\hat{T} = \hat{T}^\dagger$

then we get $\lambda \in \mathbb{R}$, i.e. λ is real.

Proof: $\rightarrow \hat{T}|\alpha\rangle = \lambda|\alpha\rangle$

$$\Rightarrow \langle \alpha | \hat{T} | \alpha \rangle = \lambda \langle \alpha | \alpha \rangle$$

$$[\langle \alpha | \hat{T} | \alpha \rangle]^\dagger = \langle \alpha | \hat{T}^\dagger | \alpha \rangle = \langle \alpha | \hat{T} | \alpha \rangle$$

$$\Rightarrow [\langle \alpha | \hat{T} | \alpha \rangle]^\dagger = \langle \alpha | \hat{T} | \alpha \rangle$$

$$\Rightarrow \lambda^\dagger \langle \alpha | \alpha \rangle = \lambda \langle \alpha | \alpha \rangle$$

$$\Rightarrow \lambda^\dagger = \lambda \quad \Rightarrow \lambda^* = \lambda \quad \Rightarrow \lambda \in \mathbb{R}.$$

Typically a linear Hermitian operator has n eigenvalues and n corresponding eigenvectors which are linearly independent. Hence they form a basis in the n dimensional space.

We write these n equations as

$$\hat{T}|e_i\rangle = \lambda_i|e_i\rangle, \quad i=1, 2, \dots, n.$$

$$\therefore (\hat{T} - \lambda_i)|e_i\rangle = 0$$

$$\Rightarrow \hat{T}|e_i\rangle = \lambda_i|e_i\rangle$$

$$\Rightarrow (\hat{T} - \lambda_i \hat{I})|e_i\rangle = 0$$

Since $|e_i\rangle \neq 0$ the only way to satisfy the eigenvalue equation is if

$$\hat{T} - \lambda_i \hat{I} = \hat{O} \quad \text{where } \hat{O} \text{ is the}$$

null operator defined $\hat{O}|\alpha\rangle = 0$

$\forall |\alpha\rangle \in S$. This is only true \forall eigenvectors

$|e_i\rangle$ of \hat{T} . Since the eigenvectors are linearly independent the condition for solution of such an equation is

$$\det(\hat{T} - \lambda_i \hat{I}) = 0$$

where $\det(\bar{m})$ means the determinant of matrix \bar{m} .

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The inverse of an operator \hat{T} or matrix \bar{T} is defined by the equation

$$\hat{T}^{-1} \hat{T} = \hat{T} \hat{T}^{-1} = \hat{I} \quad \text{or}$$

$$\bar{T}^{-1} \bar{T} = \bar{T} \bar{T}^{-1} = \bar{I},$$

$$\bar{T}^{-1} = \frac{\bar{T}_c^T}{\det(\bar{T})} \quad \text{where } \bar{T}_c \text{ is defined}$$

as the co-factor matrix of \bar{T} and \bar{T}_c^T is the transpose of \bar{T}_c .